

(K)

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:

[Upadhyaya and Singh] [Singh and Kakran] [Sisodia and Dwivedi]

, (K)

(K)

(MSE)

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. , (K)

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New Ratio Estimators in Simple Random Sampling Using (K) Factor

Abstract :

In this research we find alternative ratio estimators to the suggested estimators for [Sisodia and Dwivedi] , [Singh and Kakran] and [Upadhyaya and Singh] , in simple random sampling by using (K) factor. We obtain mean square error (MSE) equation for all proposed estimators and find the theoretical conditions for (K) factor , which makes our proposed estimator more precise than the traditional and suggested estimators .

Keywords: Simple Random Sampling ; Ratio Estimator ; (K) Factor ; Mean Square Errors

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Ratio estimator :_____ **-2**

[1993] :

$$R = \frac{\bar{Y}}{\bar{X}} = \frac{\sum_{i=1}^N Y_i}{\sum_{i=1}^N X_i} \dots\dots\dots(1)$$

(Y₁, Y₂, Y₃,..., Y_N) :
(X₁, X₂, X₃,..., X_N)

(X) (Y)

: (N)

: ()

$$\hat{R} = \frac{\bar{y}}{\bar{x}} = \frac{\sum_{i=1}^n y_i}{\sum_{i=1}^n x_i} \dots\dots\dots(2)$$

: (n)

:

$$\hat{\bar{Y}}_R = \hat{R}\bar{X} = \frac{\bar{y}}{\bar{x}} \bar{X} \dots\dots\dots(3)$$

: (MSE)

$$MSE(\hat{\bar{Y}}_R) \cong E[\hat{\bar{Y}}_R - \bar{Y}]^2 = \frac{(1-f)}{n} [\sigma^2_{(y)} - 2R\sigma_{(xy)} + R^2\sigma^2_{(x)}] \dots\dots\dots(4)$$

:

$$: f = \frac{n}{N}$$

$$: (\sigma^2_{(x)}, \sigma^2_{(y)})$$

$$: (\sigma_{(x,y)})$$

New Ratio estimators : **-3**

[Kim , Sugur and Heu , (2007)] [Kadilar and Cingi ;2003]

:

[Sesodia and Dwivedi , (1981)] •

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$$\hat{\bar{Y}}_{R(SD)} = \bar{y} \frac{\bar{X} + C_{(x)}}{\bar{x} + C_{(x)}} \dots\dots\dots(5)$$

:

...

$$\text{MSE}(\hat{\bar{Y}}_{\text{R(SD)}}) \cong \frac{(1-f)}{n} \bar{Y}^2 [C_{(y)}^2 + C_{(x)}^2 \alpha (\alpha - 2Z)] \dots \dots \dots (6)$$

:

$$\alpha = \frac{\bar{X}}{\bar{X} + C_{(x)}}, \quad Z = \rho \frac{C_{(y)}}{C_{(x)}}$$

.

: $C_{(x)}, C_{(y)}$

.(X) (Y)

: ρ

Singh and Kakran

[Sesodia and Dwivedi , (1981)]

•

(5)

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$$\hat{\bar{Y}}_{\text{R(SK)}} = \bar{y} \frac{\bar{X} + \beta_{2(x)}}{\bar{X} + \beta_{2(x)}} \dots \dots \dots (7)$$

:

$$\text{MSE}(\hat{\bar{Y}}_{\text{R(SK)}}) \cong \frac{(1-f)}{n} \bar{Y}^2 [C_{(y)}^2 + C_{(x)}^2 \delta (\delta - 2Z)] \dots \dots \dots (8)$$

:

$$\delta = \frac{\bar{X}}{\bar{X} + \beta_{2(x)}}$$

.

: $\beta_{2(x)}$

:

[Upadhyaya and Singh , (1999)]

•

$$\hat{\bar{Y}}_{\text{R(US1)}} = \bar{y} \frac{\bar{X} \beta_{2(x)} + C_{(x)}}{\bar{X} \beta_{2(x)} + C_{(x)}} \dots \dots \dots (9)$$

$$\hat{\bar{Y}}_{\text{R(US2)}} = \bar{y} \frac{\bar{X} C_{(x)} + \beta_{2(x)}}{\bar{X} C_{(x)} + \beta_{2(x)}} \dots \dots \dots (10)$$

:

$$\text{MSE}(\hat{\bar{Y}}_{\text{R(US1)}}) \cong \frac{(1-f)}{n} \bar{Y}^2 [C_{(y)}^2 + C_{(x)}^2 \omega_1 (\omega_1 - 2Z)] \dots \dots \dots (11)$$

$$\text{MSE}(\hat{\bar{Y}}_{\text{R(US2)}}) \cong \frac{(1-f)}{n} \bar{Y}^2 [C_{(y)}^2 + C_{(x)}^2 \omega_2 (\omega_2 - 2Z)] \dots \dots \dots (12)$$

:

$$\omega_1 = \frac{\bar{X} C_{(x)}}{\bar{X} C_{(x)} + \beta_{2(x)}}, \quad \omega_2 = \frac{\bar{X} \beta_{2(x)}}{\bar{X} \beta_{2(x)} + C_{(x)}}$$

[Prasad , (1989)] •

$$\hat{Y}_{R(P)} = K \hat{Y}_R \dots\dots\dots(13)$$

$$MSE(\hat{Y}_{R(P)}) \cong K^2 \frac{(1-f)}{n} [\sigma^2_{(y)} - 2R\sigma_{(xy)} + R^2\sigma^2_{(x)}] \dots\dots\dots(14)$$

$$: (K)$$

$$K = \frac{1 + \gamma \rho C_{(x)} C_{(y)}}{\gamma C_{(y)}^2 + 1}$$

$$\gamma = \frac{1-f}{n}$$

The Suggested estimators : _____ -3

(9) (7) (5)

$$: (K) . (10)$$

$$\hat{Y}_{R(SD)}^* = K_1 (\bar{y} \frac{\bar{X} + C_{(x)}}{\bar{x} + C_{(x)}}) \dots\dots\dots(15)$$

$$\hat{Y}_{R(SK)}^* = K_2 (\bar{y} \frac{\bar{X} + \beta_{2(x)}}{\bar{x} + \beta_{2(x)}}) \dots\dots\dots(16)$$

$$\hat{Y}_{R(US1)}^* = K_3 (\bar{y} \frac{\bar{X} \beta_{2(x)} + C_{(x)}}{\bar{x} \beta_{2(x)} + C_{(x)}}) \dots\dots\dots(17)$$

$$\hat{Y}_{R(US2)}^* = K_4 (\bar{y} \frac{\bar{X} C_{(x)} + \beta_{2(x)}}{\bar{x} C_{(x)} + \beta_{2(x)}}) \dots\dots\dots(18)$$

$$\begin{aligned} MSE(\hat{Y}_{R(SD)}^*) &= E(\hat{Y}_{R(SD)}^* - \bar{Y})^2 \\ &= E(K_1 \hat{Y}_{R(SD)} - \bar{Y})^2 \\ &= E(K_1^2 \hat{Y}_{R(SD)}^2 - 2 K_1 \hat{Y}_{R(SD)} \bar{Y} + \bar{Y}^2) \\ &= K_1^2 E(\hat{Y}_{R(SD)}^2) - 2 K_1 \bar{Y} E(\hat{Y}_{R(SD)}) + \bar{Y}^2 \\ &: [E(\hat{Y}_{R(SD)}) = \bar{Y}] (K_1^2 \bar{Y}^2) \end{aligned}$$

...

$$\begin{aligned}
\text{MSE}(\hat{\bar{Y}}_{R(SD)}^*) &= K_1^2 E(\hat{\bar{Y}}_{R(SD)}^2) - 2 K_1 \bar{Y} \bar{Y} + \bar{Y}^2 + K_1^2 \bar{Y}^2 - K_1^2 \bar{Y}^2 \\
&= K_1^2 E(\hat{\bar{Y}}_{R(SD)}^2) - 2 K_1 \bar{Y}^2 + \bar{Y}^2 + K_1^2 \bar{Y}^2 - K_1^2 \{E(\hat{\bar{Y}}_{R(SD)})\}^2 \\
&= K_1^2 [E(\hat{\bar{Y}}_{R(SD)}^2) - \{E(\hat{\bar{Y}}_{R(SD)})\}^2] + \bar{Y}^2 (K_1 - 1)^2 \\
&= K_1^2 \text{MSE}(\hat{\bar{Y}}_{R(SD)}) + \bar{Y}^2 (K_1 - 1)^2 \\
\therefore \text{MSE}(\hat{\bar{Y}}_{R(SD)}^*) &\cong K_1^2 [\gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \alpha (\alpha - 2Z)\}] + \bar{Y}^2 (K_1 - 1)^2 \dots\dots\dots (19) \\
&\quad (K_1)
\end{aligned}$$

$$K_1 \quad (19)$$

:

$$\begin{aligned}
\frac{\partial \text{MSE}(\hat{\bar{Y}}_{R(SD)}^*)}{\partial K_1} &= 2K_1 [\gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \alpha (\alpha - 2Z)\}] + 2\bar{Y}^2 (K_1 - 1) = 0 \\
2K_1 \text{MSE}(\hat{\bar{Y}}_{R(SD)}) + 2\bar{Y}^2 K_1 - 2\bar{Y}^2 &= 0 \\
2K_1 [\text{MSE}(\hat{\bar{Y}}_{R(SD)}) + \bar{Y}^2] &= 2\bar{Y}^2 \\
\therefore K_1 &= \frac{\bar{Y}^2}{\bar{Y}^2 + \text{MSE}(\hat{\bar{Y}}_{R(SD)})} = \frac{\bar{Y}^2}{\bar{Y}^2 + \gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \alpha (\alpha - 2Z)\}} \dots\dots\dots (20)
\end{aligned}$$

$$. (0 < K_1 < 1) :$$

:

$$\text{MSE}(\hat{\bar{Y}}_{R(SK)}^*) \cong K_2^2 [\gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \delta (\delta - 2Z)\}] + \bar{Y}^2 (K_2 - 1)^2 \dots\dots\dots (21)$$

$$\text{and } K_2 = \frac{\bar{Y}^2}{\bar{Y}^2 + \text{MSE}(\hat{\bar{Y}}_{R(SK)})} = \frac{\bar{Y}^2}{\bar{Y}^2 + \gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \delta (\delta - 2Z)\}} \dots\dots\dots (22)$$

$$\text{MSE}(\hat{\bar{Y}}_{R(US1)}^*) \cong K_3^2 [\gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \omega_1 (\omega_1 - 2Z)\}] + \bar{Y}^2 (K_3 - 1)^2 \dots\dots\dots (23)$$

$$\text{and } K_3 = \frac{\bar{Y}^2}{\bar{Y}^2 + \text{MSE}(\hat{\bar{Y}}_{R(US1)})} = \frac{\bar{Y}^2}{\bar{Y}^2 + \gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \omega_1 (\omega_1 - 2Z)\}} \dots\dots\dots (24)$$

$$\text{MSE}(\hat{\bar{Y}}_{R(US2)}^*) \cong K_4^2 [\gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \omega_2 (\omega_2 - 2Z)\}] + \bar{Y}^2 (K_4 - 1)^2 \dots\dots\dots (25)$$

$$\text{and } K_4 = \frac{\bar{Y}^2}{\bar{Y}^2 + \text{MSE}(\hat{\bar{Y}}_{R(US2)})} = \frac{\bar{Y}^2}{\bar{Y}^2 + \gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \omega_2 (\omega_2 - 2Z)\}} \dots\dots\dots (26)$$

Precision of Suggested Estimators :

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$$\text{Let } \vartheta_1 = [\gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \alpha (\alpha - 2Z)\}]$$

$$\text{MSE}(\hat{\bar{Y}}_{R(SD)}^*) < \text{MSE}(\hat{\bar{Y}}_{R(SD)})$$

$$\text{MSE}(\hat{\bar{Y}}_{R(SD)}^*) - \text{MSE}(\hat{\bar{Y}}_{R(SD)}) < 0$$

$$K_1^2 \text{MSE}(\hat{\bar{Y}}_{R(SD)}) + \bar{Y}^2 (K_1 - 1)^2 - \text{MSE}(\hat{\bar{Y}}_{R(SD)}) < 0$$

$$K_1^2 \vartheta_1 - \vartheta_1 + \bar{Y}^2 (K_1 - 1)^2 < 0$$

$$\vartheta_1 (K_1^2 - 1) + \bar{Y}^2 (K_1 - 1)^2 < 0$$

$$\vartheta_1 (K_1 - 1)(K_1 + 1) + \bar{Y}^2 (K_1 - 1)(K_1 - 1) < 0$$

$$(K_1 - 1)[\vartheta_1 (K_1 + 1) + \bar{Y}^2 (K_1 - 1)] < 0$$

$$: \quad . \quad (0 < K_1 < 1) \quad (K_1 - 1) < 0$$

$$\vartheta_1 (K_1 + 1) + \bar{Y}^2 (K_1 - 1) > 0$$

$$\vartheta_1 K_1 + \vartheta_1 + \bar{Y}^2 K_1 - \bar{Y}^2 > 0$$

$$\vartheta_1 K_1 + \bar{Y}^2 K_1 + \vartheta_1 - \bar{Y}^2 > 0$$

$$K_1 (\bar{Y}^2 + \vartheta_1) - (\bar{Y}^2 - \vartheta_1) > 0$$

$$\therefore K_1 > \frac{(\bar{Y}^2 - \vartheta_1)}{(\bar{Y}^2 + \vartheta_1)} \dots\dots\dots (27)$$

:

$$K_2 > \frac{(\bar{Y}^2 - \vartheta_2)}{(\bar{Y}^2 + \vartheta_2)} \dots\dots\dots (28)$$

$$K_3 > \frac{(\bar{Y}^2 - \vartheta_3)}{(\bar{Y}^2 + \vartheta_3)} \dots\dots\dots (29)$$

$$K_4 > \frac{(\bar{Y}^2 - \vartheta_4)}{(\bar{Y}^2 + \vartheta_4)} \dots\dots\dots (30)$$

:

$$\vartheta_2 = [\gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \delta (\delta - 2Z)\}]$$

$$\vartheta_3 = [\gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \omega_1 (\omega_1 - 2Z)\}]$$

$$\vartheta_4 = [\gamma \bar{Y}^2 \{C_{(y)}^2 + C_{(x)}^2 \omega_2 (\omega_2 - 2Z)\}]$$

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(30) , (29) , (28) , (27) ()

[Sisodia and Dwivedi]

, [Upadhyaya and Singh] [Singh and Kakran]

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(y)

(2) (1) , (20) (106) (x)
: (MSE) (3)

[Kadilar and Cingi ;2003]

(1)

N = 106	$\bar{Y} = 2212.59$	$\alpha = 0.9999$	R = 0.0807
n = 20	$\bar{X} = 27421.70$	$\delta = 0.9987$	$R_{SD} = 0.0807$
$\rho = 0.86$	$\sigma_{(y)} = 11551.53$	$Z = 2.1377$	$R_{SK} = 0.0806$
$C_{(x)} = 5.22$	$\sigma_{(x)} = 57460.61$	$\omega_1 = 0.9999$	$R_{US1} = 0.0023$
$C_{(y)} = 2.10$	$\beta_2(x) = 34.57$	$\omega_2 = 0.9994$	$R_{US2} = 0.0385$

K

(2)

طرائق التقدير	MSE		قيم العامل K_i	ناتج الشرط $\frac{(\bar{Y}^2 - 9_i)}{(\bar{Y}^2 + 9_i)}$
	المقدّرات الاعتيادية الجديدة	المقدّرات المقترحة		
Sisodia-dwivedi	2542917.924	1673595.408	0.65814	0.2223
Singh-Kakran	2545275.812	1674616.399	0.65793	0.2218
Upadhyaya-Singh1	2542769.734	1673531.219	0.65815	0.2223
Upadhyaya-Singh2	2543961.235	1674047.253	0.65805	0.2221

Prasad

K

(3)

طرائق التقدير	MSE	(K)	نتائج الشرط $\frac{(\bar{Y}^2 - 9)}{(\bar{Y}^2 + 9)}$
Prasad	1675991.788	0.65765	0.2212
Traditional	2548454.516		

(2)

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(27) ، (28) ، (29) ، (30) .
(Prasad) (3)

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(30)

(204) ، (4) (5) (6)

:

[Kadilar and Cingi ;2003]

(4)

N = 204	$\bar{Y} = 967$	$\alpha = 0.999935$	R = 0.036572
n = 30	$\bar{X} = 26441$	$\delta = 0.998962$	$R_{SD} = 0.03657$
$\rho = 0.71$	$\sigma_{(y)} = 2390$	$Z = 1.019593$	$R_{SK} = 0.036534$
$C_x = 1.72$	$\sigma_{(x)} = 45403$	$\omega_1 = 0.999998$	$R_{US1} = 0.001331$
$C_y = 2.47$	$\beta_2(x) = 27.47$	$\omega_2 = 0.999396$	$R_{US2} = 0.02125$

K

(5)

طرائق التقدير	MSE		قيم العامل K_i	نتائج الشرط $\frac{(\bar{Y}^2 - 9_i)}{(\bar{Y}^2 + 9_i)}$
	المقدرات الاعتيادية الجديدة	المقدرات المقترحة		
Sisodia-dwivedi	80464.232	74088.896	0.920768	0.830953
Singh-Kakran	80467.314	74091.510	0.920765	0.830946
Upadhyaya-Singh1	80464.038	74088.732	0.920768	0.830953
Upadhyaya-Singh2	80465.920	74090.328	0.920767	0.830949

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Prasad K (6)

طرائق التقدير	MSE	(K)	نتائج الشرط $\frac{(\bar{Y}^2 - 9)}{(\bar{Y}^2 + 9)}$
Prasad	74181.344	0.920669	0.830731
Traditional	80573.286		

(6) (5)

(Prasad)

, (29) , (28) , (27)

. (30)

-6 :

(1000) , (Normal Distribution)
(Y) (X)

(20)

:

[Law and Kelton , (2000)]

:

(7)

N = 1000	$\bar{Y} = 398.974$	$\alpha = 0.9999958$	R = 0.002085
n = 20	$\bar{X} = 191378.4$	$\delta = 0.9999962$	$R_{SD} = 0.002085$
$\rho = 0.97$	$\sigma_{(y)} = 179.974$	$Z = 0.542035$	$R_{SK} = 0.002085$
$C_x = 0.80725$	$\sigma_{(x)} = 154490.3$	$\omega_1 = 0.999994$	$R_{US1} = 0.00284$
$C_y = 0.45109$	$\beta_2(x) = 0.734$	$\omega_2 = 0.999995$	$R_{US2} = 0.00258$

K

(8)

	MSE		
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	المقدّرات الاعتيادية الجديدة	المقدّرات المقترحة	K_i	$\frac{(\bar{Y}^2 - 9_i)}{(\bar{Y}^2 + 9_i)}$
Sisodia-dwivedi	1159.796	1151.406	0.99277	0.9854302
Singh-Kakran	1159.797	1151.408	0.99277	0.9854302
Upadhyaya-Singh1	1159.789	1151.399	0.99277	0.9854303
Upadhyaya-Singh2	1159.793	1151.404	0.99277	0.9854302

Prasad K (9)

طرائق التقدير	MSE	(K)	نتائج الشرط $\frac{(\bar{Y}^2 - 9)}{(\bar{Y}^2 + 9)}$
Prasad	1151.426	0.99277	0.9854299
Traditional	1159.815		

(8)

(9) . (30) , (29) , (28) , (27)

(Prasad)

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, (Uniform Distribution)

(Y) (X) (5000)

(500)

: (12) (11) (10)

(10)

N = 5000	$\bar{Y} = 3.40E+07$	$\alpha = 0.99989$	R = 6761.369
n = 500	$\bar{X} = 5028.567$	$\delta = 1.00023$	$R_{SD} = 6760.602$
$\rho = 0.97$	$\sigma_{(y)} = 3.00E+07$	Z = 1.50003	$R_{SK} = 6762.925$
$C_x = 0.570576$	$\sigma_{(x)} = 2869.18$	$\omega_1 = 1.000098$	$R_{US1} = -5844.453$
$C_y = 0.882353$	$\beta_2(x) = -1.157$	$\omega_2 = 1.000403$	$R_{US2} = 11854.856$

K (11)

طرائق التقدير	MSE		قيم العامل K_i	نتائج الشرط $\frac{(\bar{Y}^2 - 9_i)}{(\bar{Y}^2 + 9_i)}$
	المقدّرات الاعتيادية	المقدّرات المقترحة		

Sisodia-dwivedi	2.65195E+11	2.65135E+11	0.99977	0.9995412
Singh-Kakran	2.64963E+11	2.64902E+11	0.99977	0.9995416
Upadhyaya-Singh1	2.65052E+11	2.64991E+11	0.99977	0.9995414
Upadhyaya-Singh2	2.64845E+11	2.64785E+11	0.99977	0.9995418

Prasad K (12)

طرائق التقدير	MSE	(K)	نتائج الشرط $\frac{(\bar{Y}^2 - 9)}{(\bar{Y}^2 + 9)}$
Prasad	2.65058E+11	0.99977	0.9995413
Traditional	2.65118E+11		

(8)

. (30) , (29) , (28) , (27)

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" " (1993) -1

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